Caribou
Odyssey III Class,
Autonomous Underwater Vehicle

Caribou is the AUV Lab's newest vehicle. Recently built by Bluefin Robotics Corporation this AUV represents the culmination of significant development efforts. Featuring a modular hull design and the latest evolution of AUV navigation, propulsion and power systems, *Caribou* provides significant new autonomous survey capabilities and flexibility for other scientific needs.

Equipped with state-of-the-art sensors this AUV can collect high-quality data. *Caribou's* modular payload sections allow one core vehicle to support widely different science missions. The initial section is designed to accommodate the Edgetech® FS-AU side-scan sonar and sub-bottom profiler. Additional payload modules are being designed. The AUV Lab is looking forward to applying *Caribou* to a wide spectrum of research efforts including: archaeological remote sensing, multi-static acoustic modeling, fisheries resource studies and development of concurrent mapping and localization techniques.

Specifications

Length (Base):	2.6 m (103 inches)
(w/ sonar payload):	3.4 m (135 inches)
Diameter:	0.58 m (23 inches)
Weight in air:	~400 kg (881 lbs)
Buoyancy:	~+0.5 kg (+1lbs.)
Maximum Depth:	4500 m
Operation Depth:	3000 m
Survey Speed:	3-4 knots
Survey Endurance:	20 hours (at 3 knots)

Batteries:	Lithium Polymer
Line Keeping:	+/- 2 meters
Altitude Keeping:	+/- 1 meter

Payload:
Designed to accommodate various sonar, camera, and oceanographic systems in modular sections.

MIT Sea Grant AUV Lab
292 Main St.
Room E38-300
Cambridge, MA 02142

Phone: (617) 253-3402
Fax: (617) 258-5730
Email: auvlab@mit.edu
http://web.mit.edu/seagrant/